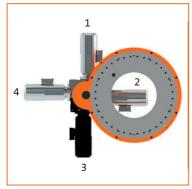
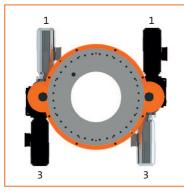
## FIBROMAT<sup>®</sup> AT.1250

# **FIBRO**



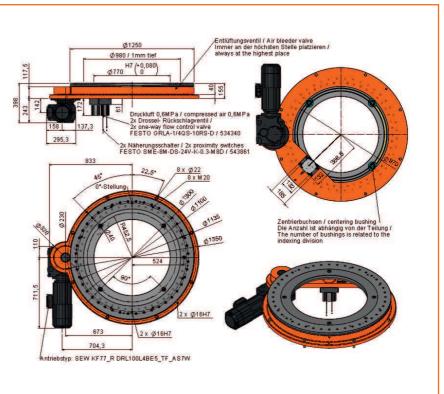
FIBROMAT AT.1250 Drive arrangement 10, 20, **30**, 40



FIBROMAT AT.1250 Drive arrangement 11, 13, **31**, 33

#### **Dimensions of FIBROMAT° AT.1250**

(Drive arrangement 180° with one drive; for other drive arrangements, diagrams or CAD data are available)



Technical data for FIBROMAT® A	AT.1250 Co	oding AT.1250 .						
Table top dimension	Ø 1,250 mm							
1 drive with motor SIEMENS Motor 1FK7105-5A 1 drive with motor Special motor 2 drives without motor Gearboxes prepared for moto			ear motor KF77/R DRL 132S4BE5/TF/AS7W/Z D5-5AF71-1EH0 motors according to customer ear motor KF77/R DRL 132S4BE5/TF/AS7W/Z	.10 .11 .12 .19 .20 .21 .22 .29	2			
Drive arrangement	See pictures above Special design							
<b>Divisions</b> Any, maximum 30	Without indexing unit With indexing unit for division XX, symmetrical arrangement Special division				4			
Centre hole	Ø 770 mm Extended by 200 mm (not combinable with standard indexing unit) Special design				5			
Measuring system	Measuring system on motor With additional direct measuring system (mounted in standard centre hole) With measuring system in special design				6			
Direction of rotation	Any							
Mounting position	Any, standard table top: (Please state other mour	horizontal nting positions when orde	ring)					
Indexing and repeat accuracy No indexing, one drive No indexing, two drives With indexing, one drive With two drives, with measuring system	Indexing accuracy Repeat accuracy   ±290" ±145"   ±60" ±30"   ±15" ±8"   ±10" ±5"							

#### Technical data for FIBROMAT<sup>®</sup> AT.1250

Maximum axial runout of the table top	0.07 mm	
Maximum runout of the centre hole	0.07 mm	
Weight	FIBROMAT AT.1250 Gear motor Indexing unit	635 kg 112 kg 25 kg

## Indexing times for FIBROMAT<sup>®</sup> AT.1250

AT.1250 with one drive										
45°	t₅ in s	3.7	3.4	3.1	2.8	2.5	2.3	2.0	17	1.3
	J in kgm <sup>2</sup>	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
90°	t₅ in s	5.2	4.8	4.4	3.9	3.6	3.3	3.0	2.3	1.9
	J in kgm <sup>2</sup>	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
180°	t₅ in s	7.3	6.9	6.4	5.9	5.6	5.3	4.4	3.5	3.0
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000

#### AT.1250 with two drives

45°	t₅ in s	2.5	2.3	2.1	1.9	1.7	1.6	1.5	1.1	0.9
	J in kgm <sup>2</sup>	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
90°	t₅ in s	3.5	3.3	3.1	2.9	2.7	2.6	2.1	1.7	1.5
	J in kgm <sup>2</sup>	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
180°	t₅ in s	5.5	5.3	5.1	4.9	4.7	4.6	3.2	2.8	2.6
	J in kgm <sup>2</sup>	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000

The specified switching times do not include: Regulation time of 0.1 sec, indexing time of 0.3 sec. Further angels and indexing times can be calculated for you.

### Load data for FIBROMAT<sup>®</sup> AT.1250

Perm. transport load on table top horizontal	15,000 kg
Perm. superstructure diameter	7,500 mm
Perm. force vertically on rotating table top	172,000 N
Perm. radial force on the rotating table top	80,000 N
Perm. tilting moment on rotating table top	72,000 Nm
Perm. tangential moment on table top (dynamic)	12,900 Nm

We would be pleased to provide a calculation of combined load data for your specific application.

## Additional options for FIBROMAT<sup>®</sup> AT.1250

Drive unit Asynchronous motor (standard)	Indexing unit	
Drive unit Synchronous servomotor	<b>Machine stands</b> Height: 457 mm	risno
Drive inverter	Additional table top	